

Problem Set I: Due Thursday, January 16, 2014

- 1.) Determine the stable equilibrium positions for a simple pendulum which oscillates:
- horizontally, with $x = x_0 \cos \omega t$
 - in a circle, with $x = r_0 \cos \omega t$, $y = r_0 \sin \omega t$.

Take $\omega \gg \sqrt{g/\ell}$ and consider the full range of parameters.

- 2.) Now again consider a simple pendulum with support oscillating at $y = y_0 \cos \omega t$. If the pendulum has length ℓ (so $\omega_0 = \sqrt{g/\ell}$) and $\omega = 2\omega_0 + \epsilon$, determine the conditions for, and growth rate of, parametric instability.
- 3.) Compute the threshold for parametric instability in the presence of linear frictional damping, as well as mismatch. For what range of mismatch ϵ will instability occur?
- 4.) Let $H(q, p, t) = H_0(q, p) + V(q) d^2 A / dt^2$ where $A(t)$ is periodic, with period $\tau \ll T$. Here T is the period of the motion governed by H_0 .
- Derive the mean field (i.e. short time averaged) equations for this system.
 - Show that these mean field equations may be obtained from the effective Hamiltonian

$$K(p, q) = H_0(p, q) + \frac{1}{4m} \left\langle \left(\frac{dA}{dt} \right)^2 \right\rangle \left(\frac{\partial V(q)}{\partial q} \right)^2.$$

Here $\langle \rangle$ means a short time average. You may assume $H_0 = p^2/2m + V_0(q)$.

- 5.) Consider the asymmetric top, with moments of inertia $I_1 < I_2 < I_3$. Here 1, 2, 3 refer to the principal axes in a frame for which the inertia tensor is diagonal. Using the Euler equations:
- Derive the equations of motion for $\Omega_1(t)$, $\Omega_2(t)$, $\Omega_3(t)$, the angular frequencies associated with axes 1, 2, 3.
 - Show that if $\Omega_2 \cong \Omega_0$ while Ω_1 , Ω_2 start from an infinitesimal perturbation, instability results. Show that $\Omega_1 \cong \Omega_0$ or $\Omega_3 \cong \Omega_0$ is stable.
 - What are the two conserved quantities which constrain the evolution in b.)?
- 6.) Consider a free nonlinear oscillator which satisfied the equation

$$\ddot{x} + \omega_0^2 x = -\alpha x^2 - \beta x^3.$$

Use Poincare-Linstedt perturbation theory to calculate the non-linear frequency shift and lowest order non-trivial solution.